

Communication Protocol

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1 Introduction

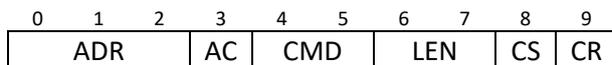
The new communication protocol is introduced in Thyracont Smartline Devices from a specific firmware version on and is usable besides the old protocol. **But it is strongly recommended to either use the old or the new communication protocol and not a mixture of both.**

E.g. the old commands for *Switchpoint*, *Setpoint* and *Hysteresis* have been superseded by a unique new command *Relay* and their respective read and write commands are not compatible to each other anymore. The new protocol has a completely new syntax with a 1 byte access code (AC), 2 bytes command (CMD) and 2 bytes data field length. The new syntax is described below.

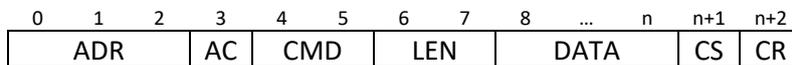
2 Syntax

2.1 Package

For packages without data:



For packages with data:



The bytes are summarized by the following table:

| Syntax Part | Byte (with data) | Byte (without data) | Description |
|----------------------|------------------|---------------------|---|
| Address (ADR) | 0-2 | 0-2 | Address for communication |
| Access Code (AC) | 3 | 3 | Access type |
| Command (CMD) | 4-5 | 4-5 | Character codes command |
| Length (LEN) | 6-7 | 6-7 | Length of data |
| Data (DATA) | 8-n | | Data to send or receive |
| Checksum (CS) | n+1 | 8 | Checksum for byte 0 to 7 (without data) Checksum for byte 0 to n (with data) |
| Carriage Return (CR) | n+2 | 9 | Carriage return, mandatory |

2.2 Address (ADR)

The address consists of 3 bytes.

| | |
|---------------|--------------|
| Address (ADR) | |
| 001 | RS232 or USB |
| 001-016 | RS485 |
| 100 | VD12 (USB) |

2.3 Access Code (AC)

The byte access code differs between read, write, factory default, error and binary mode. If you want to send a package with a read command from your master to the transmitter you must use "0" (zero) as access code. If the transmitter has executed the command it will answer and increase the access code by one. Thus, the received package has access code "1". The same applies for the write command. From master to transmitter you must use "2" for a write command, and the received feedback from the transmitter contains "3" as access code.

Factory default is an option for some commands to reset a parameter to its default value, e.g. the gas correction factor for a Pirani sensor.

If an error happens inside of any transmitter, the access code will be changed to “7” and not increased by one. The binary mode is to read and write binary data and is used for firmware update. Note: When using Binary Type of Access the length (LEN) must also be binary data of 2 bytes.

| Type of Access | Access Codes for Send Sequences Master → Transmitter | Access Codes for Receive Sequences Transmitter → Master |
|-----------------|---|--|
| Read | 0 | 1 |
| Write | 2 | 3 |
| Factory Default | 4 | 5 |
| Error | - | 7 |
| Binary | 8 | 9 |

2.4 Command (CMD)

The new command is a 2 bytes case sensitive character [AA to ZZ]. A full list of valid commands is given in the next chapter.

2.5 Length (LEN)

The new part of a package is the length of DATA in bytes. If the length is lower than 10 bytes, fill up with zeros to the left. If there is no DATA (e.g. Read Commands) use “00” as length.

2.6 Checksum (CS)

Every package contains a checksum to verify the validity of the package and the calculation formula has not changed with respect to old protocol.

Package without data: build checksum from bytes 0 to 7
 Package with data: build checksum from bytes 0 to n

The checksum equation:

$$\text{Decimal Number of CS} = \left(\sum \text{decimal numbers of characters} \right) \text{ mod } 64 + 64$$

To get the character of the checksum, convert the resulting decimal number of CS backwards into an ASCII character.

Example: Read Measurement Value (MV) at address 1

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|-----|----|----|----|-----|----|-----|----|----|----|
| ADR | | | AC | CMD | | LEN | | CS | CR |
| 0 | 0 | 1 | 0 | M | V | 0 | 0 | ? | CR |
| 48 | 48 | 49 | 48 | 77 | 86 | 48 | 48 | | |

- 1.) Calculate sum: 48+48+49+48+77+86+48+48 = 452
- 2.) Calculate decimal number of CS character: (452 mod 64) + 64 = 4 + 64 = 68
- 3.) ASCII Character of decimal 68 is uppercase “D”
- 4.) Insert “D” as checksum character

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|-----|---|---|----|-----|---|-----|---|----|----|
| ADR | | | AC | CMD | | LEN | | CS | CR |
| 0 | 0 | 1 | 0 | M | V | 0 | 0 | D | CR |
| | | | | | | | | | |

2.7 Data Source

Some commands support selecting the data source. This means the input data of this function can be set to another source of measurement data. The data source is set as an integer value corresponding to a sensor or a virtual sensor.

| Sensor Type | Data Source Value |
|---------------------------------|-------------------|
| Absolute Pressure (Combination) | 0 (default) |
| Pirani | 1 |
| Piezo | 2 |
| Hot Cathode | 3 |
| Cold Cathode | 4 |
| Ambient Pressure | 6 |
| Relative Pressure | 7 |

3 Command Overview

3.1 Main Commands

| Command | CMD | Valid Access Codes (AC) | | | | |
|------------------------------------|-----|-------------------------|-------|-----------------|-------|--------|
| | | Read | Write | Factory Default | Error | Binary |
| | | 0/1 | 2/3 | 4/5 | 7 | 8/9 |
| Measurement Range | MR | X | | | X | |
| Measurement Value | MV | X | | | X | |
| Measurement Value 1 (Pirani) | M1 | X | | | X | |
| Measurement Value 2 (Piezo) | M2 | X | | | X | |
| Measurement Value 3 (Hot Cathode) | M3 | X | | | X | |
| Measurement Value 4 (Cold Cathode) | M4 | X | | | X | |
| Measurement Value 6 (Ambient P.) | M6 | X | | | X | |
| Measurement Value 7 (Relative P.) | M7 | X | | | X | |
| Relay 1 | R1 | X | X | X | X | |
| Relay 2 | R2 | X | X | X | X | |
| Relay 3 | R3 | X | X | X | X | |
| Relay 4 | R4 | X | X | X | X | |
| Display Unit | DU | X | X | X | X | |
| Display Orientation | DO | X | X | X | X | |
| Display Data Source | DD | X | X | X | X | |
| Adjust High | AH | | X | | X | |
| Adjust Low | AL | | X | | X | |

3.2 Device Parameters

| Command | CMD | Valid Access Codes (AC) | | | | |
|-------------------|-----|-------------------------|-------|-----------------|-------|--------|
| | | Read | Write | Factory Default | Error | Binary |
| | | 0/1 | 2/3 | 4/5 | 7 | 8/9 |
| Degas | DG | X | X | | X | |
| Digital Logic | DL | X | X | | X | |
| Sensor Transition | ST | X | X | X | X | |
| Cathode Control | CC | X | X | X | X | |

| | | | | | | |
|--|----|---|---|---|---|--|
| Cathode Control Mode | CM | X | X | X | X | |
| Filament Control | FC | X | X | X | X | |
| Filament Number | FN | X | | | X | |
| Filament Status | FS | X | | | X | |
| Gas Correction Factor 1 (Pirani) | C1 | X | X | X | X | |
| Gas Correction Factor 3 (Hot Cathode) | C3 | X | X | X | X | |
| Gas Correction Factor 4 (Cold Cathode) | C4 | X | X | X | X | |
| Analog Output Characteristic | OC | X | | X | X | |
| Panel Status | PS | X | X | | X | |
| Controller Status | CS | X | X | | X | |

3.3 Device Information

| Command | CMD | Valid Access Codes (AC) | | | | |
|----------------------|-----|-------------------------|-------|-----------------|-------|--------|
| | | Read | Write | Factory Default | Error | Binary |
| | | 0/1 | 2/3 | 4/5 | 7 | 8/9 |
| Type of Device | TD | X | | | X | |
| Product Name | PN | X | | | X | |
| Serial Number Device | SD | X | | | X | |
| Serial Number Head | SH | X | | | X | |
| Baud Rate | BR | | X | | X | |
| Response Delay | RD | X | X | X | X | |
| Version Device | VD | X | | | X | |
| Version Firmware | VF | X | | | X | |
| Version Bootloader | VB | X | | | X | |
| Device Restart | DR | | X | | X | |
| Operating Hours | OH | X | | | X | |

4 Command List

4.1 Smartline Transmitter

| Name | CMD | VSR | VSL | VSP / VCP | VSH | VSM | VSI |
|------------------------------------|-----|----------------|----------------|----------------|----------------|----------------|----------------|
| Measurement Range | MR | X | X | X | X | X | X |
| Measurement Value | MV | X | X | X | X | X | X |
| Measurement Value 1 (Pirani) | M1 | X | X | X | X | X | |
| Measurement Value 2 (Piezo) | M2 | X | X | | | | |
| Measurement Value 3 (Hot Cathode) | M3 | | | | X ² | | |
| Measurement Value 4 (Cold Cathode) | M4 | | | | | X ² | X |
| Measurement Value 6 (Ambient P.) | M6 | | X | | | | |
| Measurement Value 7 (Relative P.) | M7 | | X | | | | |
| Relay 1 | R1 | X | X | X | X | X | X |
| Relay 2 | R2 | X | X | X | X | X | X |
| Display Unit | DU | X ¹ |
| Display Orientation | DO | X ¹ |
| Display Data Source | DD | X ¹ |
| Adjust High | AH | X | X | X | X | X | |
| Adjust Low | AL | X | X | X | X | X | |

| | | | | | | | |
|--|----|---|---|---|---|---|---|
| Degas | DG | | | | X | | |
| Digital Logic | DL | | X | | X | X | X |
| Sensor Transition | ST | X | X | | X | X | |
| Cathode Control | CC | | | | X | X | X |
| Cathode Control Mode | CM | | | | | X | X |
| Filament Control | FC | | | | X | | |
| Filament Number | FN | | | | X | | |
| Filament Status | FS | | | | X | | |
| Gas Correction Factor 1 (Pirani) | C1 | X | X | X | X | X | |
| Gas Correction Factor 3 (Hot Cathode) | C3 | | | | X | | |
| Gas Correction Factor 4 (Cold Cathode) | C4 | | | | | X | X |
| Analog Output Characteristic | OC | X | X | X | X | X | X |
| Operating Hours | OH | X | X | X | X | X | X |

| | | | | | | | |
|----------------------|----|---|---|---|---|---|---|
| Type of Device | TD | X | X | X | X | X | X |
| Product Name | PN | X | X | X | X | X | X |
| Serial Number Device | SD | X | X | X | X | X | X |
| Serial Number Head | SH | X | X | X | X | X | X |
| Baud Rate | BR | X | X | X | X | X | X |
| Response Delay | RD | X | X | X | X | X | X |
| Version Device | VD | X | X | X | X | X | X |
| Version Firmware | VF | X | X | X | X | X | X |
| Version Bootloader | VB | X | X | X | X | X | X |
| Device Restart | DR | X | X | X | X | X | X |

Notes:

- 1) Only valid if device has an LCD display
- 2) Only valid if cathode is not switched off permanently

4.2 Display and Control Units

| Name | CMD | VD12 | VD14 |
|-------------------|------------|-------------|-------------|
| Relay 1 | R1 | X | X |
| Relay 2 | R2 | X | X |
| Relay 3 | R3 | | X |
| Relay 4 | R4 | | X |
| Display Unit | DU | X | X |
| Panel Status | PS | X | X |
| Controller Status | CS | X | X |

| | | | |
|--------------------|----|---|---|
| Type of Device | TD | X | X |
| Product Name | PN | X | X |
| Version Device | VD | X | X |
| Version Firmware | VF | X | X |
| Version Bootloader | VB | X | X |
| Device Restart | DR | X | X |

5 Command Descriptions

5.1 Main Commands

5.1.1 Measurement Range (MR)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------------|--|
| Read | Send | 0 | MR | no data | |
| | Receive | 1 | MR | H[float]L[float] | H followed by upper limit as float [mbar] L followed by lower limit as float [mbar] |
| | | 7 | MR | Error Code | See Error Messages |

Example: Read Measurement Range VSR53D, Address 1

Sequence Send:

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|-----|----|-----|-----|----|----|---|---|---|----|
| ADR | AC | CMD | LEN | CS | CR | | | | |
| 0 | 0 | 1 | 0 | M | R | 0 | 0 | @ | CR |

Sequence Receive:

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 |
|-----|----|-----|-----|------|---|---|---|---|---|----|----|----|----|----|----|----|----|----|----|----|
| ADR | AC | CMD | LEN | DATA | | | | | | | | | | | | | | CS | CR | |
| 0 | 0 | 1 | 1 | M | R | 1 | 1 | H | 1 | . | 2 | e | 3 | L | 1 | e | - | 4 | w | CR |

The transmitter VSR53D has a measurement range from 1.2e3 to 1e-4 mbar.

5.1.2 Measurement Value (MV)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | MV | no data | |
| | Receive | 1 | MV | float | Pressure [mbar] |
| | | 1 | MV | OR | Overrange |
| | | 1 | MV | UR | Underrange |
| | | 7 | MV | Error Code | See Error Messages |

Example: Read Current Pressure from VSR53D, Address 1

Sequence Send:

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|-----|----|-----|-----|----|----|---|---|---|----|
| ADR | AC | CMD | LEN | CS | CR | | | | |
| 0 | 0 | 1 | 0 | M | V | 0 | 0 | D | CR |

Sequence Receive: Pressure 973.4 mbar

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 |
|-----|----|-----|-----|------|---|---|---|---|---|----|----|----|----|----|----|----|
| ADR | AC | CMD | LEN | DATA | | | | | | | | | | | CS | CR |
| 0 | 0 | 1 | 1 | M | V | 0 | 7 | 9 | . | 7 | 3 | 4 | e | 2 | h | CR |

5.1.3 Measurement Value 1, 2, 3, 4, 6, 7 (M1, M2, M3, M4, M6, M7)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|------|---------|------------------------------|
| Read | Send | 0 | M1 | no data | Pressure Pirani [mbar] |
| | | | M2 | no data | Pressure Piezo [mbar] |
| | | | M3 | no data | Pressure Hot Cathode [mbar] |
| | | | M4 | no data | Pressure Cold Cathode [mbar] |
| | | | M6 | no data | Ambient Pressure [mbar] |
| | | | M7 | no data | Relative Pressure [mbar] |
| | Receive | 1 | M1/7 | float | Pressure Value [mbar] |

| | | | | | |
|--|--|---|------|------------|------------------------------------|
| | | 1 | M1/7 | OR | Overrange |
| | | 1 | M1/7 | UR | Underrange |
| | | 7 | M1/7 | Error Code | See Error Messages |

5.1.4 Relay 1, 2, 3, 4 (R1, R2, R3, R4)

The relays can be configured independently and can follow different operating modes. These modes depend on transmitter type and firmware version. It may be possible that not all modes are supported by your firmware; in that case your transmitter will return an error message and you must update the firmware first.

The following modes are possible:

- Switch by pressure (default)
- Switch on/off if Error
- Switch on/off if Underrange
- Switch on/off if Overrange
- Switch on/off if cathode is on
- Switch on/off if filament is defect
- Switch temporarily on/off

Apart from the default mode all others can be inverted by using an exclamation mark as prefix. The default mode can be inverted by switching both pressure values.

For control units it is necessary to specify the appropriate measurement channel. Therefore an additional measurement channel parameter is appended with the parameter prefix "C" in the data field.

| Mode | Sequence | AC | CMD | Data | Description |
|------|-----------------------------|----|------|------------------------|--|
| Read | Send | 0 | R1/4 | no data | |
| | Receive | 1 | R1/4 | T[float]F[float] | Mode: Switch by pressure (default) T followed by pressure [mbar] F followed by pressure [mbar] |
| | | | | T[float]F[float]D[int] | D (optional parameter "data source"; VSL only) |
| | | | | T[float]F[float]C[int] | C (parameter "channel"; VD12/14 only) |
| | | | | E | Mode: Switch on if Error |
| | | | | !E | Mode: Switch off if Error |
| | | | | U | Mode: Switch on if Underrange |
| | | | | !U | Mode: Switch off if Underrange |
| | | | | O | Mode: Switch on if Overrange (VSR, VSL, VSI only) |
| | | | | !O | Mode: Switch off if Overrange (VSR, VSL, VSI only) |
| | | | | C | Mode: Switch on if cathode is on (VSH, VSM/VSI only) |
| | | | | !C | Mode: Switch off if cathode is on (VSH, VSM/VSI Only) |
| | | | | W | Mode: Switch on if filament is defect (VSH only) |
| | | | | !W | Mode: Switch off if filament is defect (VSH only) |
| | | | | T0 | Mode: Temporarily, relay off |
| T1 | Mode: Temporarily, relay on | | | | |

| | | | | | |
|-----------------|-----------------------------|---|------|------------------------|---|
| | | 7 | R1/4 | Error Code | See Error Messages |
| Write | Send | 2 | R1/4 | T[float]F[float]D[int] | Mode: Switch by pressure (default) T followed by pressure [mbar] F followed by pressure [mbar] D (optional parameter "data source"; VSL only) |
| | | | | T[float]F[float]D[int] | D (optional parameter "data source"; VSL only) |
| | | | | T[float]F[float]C[int] | C (parameter "channel"; VD12/14 only) |
| | | | | E | Mode: Switch on if Error |
| | | | | !E | Mode: Switch off if Error |
| | | | | U | Mode: Switch on if Underrange |
| | | | | !U | Mode: Switch off if Underrange |
| | | | | O | Mode: Switch on if Overrange (VSR, VSL, VSI only) |
| | | | | !O | Mode: Switch off if Overrange (VSR, VSL, VSI only) |
| | | | | C | Mode: Switch on if cathode is on (VSH, VSM/VSI only) |
| | | | | !C | Mode: Switch off if cathode is on (VSH, VSM/VSI only) |
| | | | | W | Mode: Switch on if filament is defect (VSH only) |
| | | | | !W | Mode: Switch off if filament is defect (VSH only) |
| | | | | T0 | Mode: Temporarily, relay off |
| T1 | Mode: Temporarily, relay on | | | | |
| | Receive | 3 | R1/4 | no data | Write successful |
| | | 7 | R1/4 | Error Code | See Error Messages |
| Factory Default | Send | 4 | R1/4 | no data | Restore Default Mode and Default pressure values |
| | Receive | 5 | R1/4 | no data | Restore Default successful |
| | | 7 | R1/4 | Error Code | See Error Messages |

Example: Write "1E-1 mbar on and 1.5 mbar off" as relay 1 setting for VSP53DL, Address 2

Sequence Send:

| | | | | | | | | | | | | | | | | | |
|-----|---|----|-----|---|-----|---|------|---|---|----|----|----|----|----|----|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 |
| ADR | | AC | CMD | | LEN | | DATA | | | | | | | | | CS | CR |
| 0 | 0 | 2 | 2 | R | 1 | 0 | 8 | T | 0 | . | 1 | F | 1 | . | 5 | I | CR |

Sequence Receive:

| | | | | | | | | | |
|-----|---|----|-----|---|-----|---|----|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| ADR | | AC | CMD | | LEN | | CS | CR | |
| 0 | 0 | 2 | 3 | R | 1 | 0 | 0 | h | CR |

Example: Write "1E-1 mbar on, 1.5 mbar off on measurement channel 1" as relay 1 setting for VD12, Address 100

Sequence Send:

| | | | | | | | | | | | | | | | | | | | |
|-----|---|----|-----|---|-----|---|------|---|---|----|----|----|----|----|----|----|----|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 |
| ADR | | AC | CMD | | LEN | | DATA | | | | | | | | | | | CS | CR |
| 1 | 0 | 0 | 2 | R | 1 | 1 | 0 | T | 0 | . | 1 | F | 1 | . | 5 | C | 1 | X | CR |

Sequence Receive:

| | | | | | | | | | |
|-----|---|---|----|-----|---|-----|---|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| ADR | | | AC | CMD | | LEN | | CS | CR |
| 1 | 0 | 0 | 3 | R | 1 | 0 | 0 | g | CR |

5.1.5 Display Unit (DU)

| Mode | Sequence | AC | CMD | Data | Description |
|-----------------|----------|----|------------|------------------------------------|------------------------------------|
| Read | Send | 0 | DU | no data | |
| | Receive | 1 | DU | mbar | Current unit is mbar (default) |
| | | | | Torr | Current unit is Torr |
| | | | | hPa | Current unit is hPa |
| | 7 | DU | Error Code | See Error Messages | |
| Write | Send | 2 | DU | mbar | New unit is mbar (default) |
| | | | | Torr | New unit is Torr |
| | | | | hPa | New unit is hPa |
| | Receive | 3 | DU | no data | Write successful |
| | | | | 7 | DU |
| Factory Default | Send | 4 | DU | no data | Restore Default |
| | Receive | 5 | DU | no data | Restore Default successful |
| | | 7 | DU | Error Code | See Error Messages |

Example: Write "mbar" as new display unit for VSP53DL, Address 2

Sequence Send:

| | | | | | | | | | | | | | |
|-----|---|---|----|-----|---|-----|---|------|---|----|----|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 |
| ADR | | | AC | CMD | | LEN | | DATA | | | | CS | CR |
| 0 | 0 | 2 | 2 | D | U | 0 | 4 | m | b | a | r | c | CR |

Sequence Receive:

| | | | | | | | | | |
|-----|---|---|----|-----|---|-----|---|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| ADR | | | AC | CMD | | LEN | | CS | CR |
| 0 | 0 | 2 | 3 | D | U | 0 | 0 | ~ | CR |

Valid units:

VSP/VCP, VSM/VSI, VSH: mbar, Torr, hPa, Torr760

VSR, VSL: mbar, Torr, hPa

VD12/VD14: mbar, Torr, hPa, bar, mTorr, Pa

5.1.6 Display Orientation (DO)

| Mode | Sequence | AC | CMD | Data | Description |
|-----------------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | DO | no data | |
| | Receive | 1 | DO | 0 | Not rotated (default) |
| | | | | 1 | Rotated by 180° |
| | | | | 7 | DO |
| Write | Send | 2 | DO | 0 | Not rotated (default) |
| | | | | 1 | Rotate by 180° |
| | | | | 3 | DO |
| | Receive | 7 | DO | Error Code | See Error Messages |
| | | | | 7 | DO |
| Factory Default | Send | 4 | DO | no data | Restore Default |
| | Receive | 5 | DO | no data | Restore Default successful |
| | | 7 | DO | Error Code | See Error Messages |

5.1.7 Display Data Source (DD)

| Mode | Sequence | AC | CMD | Data | Description |
|-----------------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | DD | no data | |
| | Receive | 1 | DD | Int | Data source (default: 0) |
| | | 7 | DD | Error Code | See Error Messages |
| Write | Send | 2 | DD | Int | Data source |
| | Receive | 3 | DD | no data | Write successful |
| | | 7 | DD | Error Code | See Error Messages |
| Factory Default | Send | 4 | DD | no data | Restore Default (default: 0) |
| | Receive | 5 | DD | no data | Restore Default successful |
| | | 7 | DD | Error Code | See Error Messages |

5.1.8 Adjust High (AH)

| Mode | Sequence | AC | CMD | Data | Description |
|-------|----------|----|-----|------------|---|
| Write | Send | 2 | AH | no data | Adjust High for VSP, VCP, VSM, VSH Adjust Relative (VSL only) |
| | | | AH | float | Adjust High for VSR, VSL; pressure in [mbar] |
| | Receive | 3 | AH | no data | Adjust High successful |
| | | 7 | AH | Error Code | See Error Messages |

Example: Adjust High with 981.5 mbar for VSR53D, Address 1

Sequence Send:

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 |
|-----|---|---|----|-----|---|-----|---|------|---|----|----|----|----|----|
| ADR | | | AC | CMD | | LEN | | DATA | | | | | CS | CR |
| 0 | 0 | 1 | 2 | A | H | 0 | 5 | 9 | 8 | 1 | . | 5 | v | CR |

Sequence Receive:

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|-----|---|---|----|-----|---|-----|----|----|----|
| ADR | | | AC | CMD | | LEN | CS | CR | |
| 0 | 0 | 1 | 3 | A | H | 0 | 0 | m | CR |

5.1.9 Adjust Low (AL)

| Mode | Sequence | AC | CMD | Data | Description |
|-------|----------|----|-----|------------|--|
| Write | Send | 2 | AL | no data | Adjust to zero |
| | | | AL | float | Adjust Low to specific pressure Valid from 1E-4 to 1E-1 mbar (VSP, VCP only) |
| | Receive | 3 | AL | no data | Adjust Low successful |
| | | 7 | AL | Error Code | See Error Messages |

5.2 Sensor Parameters

5.2.1 Degas (DG)

The current pressure must be below 2E-6mbar to switch Degas on.

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | DG | no data | |
| | Receive | 1 | DG | 0 | Degas currently off |
| | | | DG | 1 | Degas currently on |
| | | 7 | DG | Error Code | See Error Messages |

| | | | | | |
|-------|---------|---|----|------------|------------------------------------|
| Write | Send | 2 | DG | 0 | Switch Degas off |
| | | | DG | 1 | Switch Degas on |
| | Receive | 3 | DG | no data | Write successful |
| | | 7 | DG | Error Code | See Error Messages |

5.2.2 Digital Logic (DL)

Digital Logic (Degas Logic) is a valid command for VSH serial numbers higher than 16580300, otherwise you will get the error message NO_DEF (see [Error Messages](#)). Furthermore, it is a valid command for VSI/VSM (Cathode Control Logic), and VSL (Adjust Control Logic) transmitter.

| Mode | Sequence | AC | CMD | Data | Description |
|-----------------|----------|----|------------|------------------------------------|--|
| Read | Send | 0 | DL | no data | |
| | Receive | 1 | DL | 0 | Degas Logic is active low (VSH) Logic is active low (VSI/VSM, VSL) |
| | | | | 1 | Degas Logic is active high (VSH) Logic is active high (VSI/VSM, VSL) |
| | | 7 | DL | Error Code | See Error Messages |
| Write | Send | 2 | DL | 0 | Set Degas Logic to active low (VSH) Set Logic to active low (VSI/VSM, VSL) |
| | | | | 1 | Set Degas Logic to active high (VSH) Set Logic to active high (VSI/VSM, VSL) |
| | Receive | 3 | DL | no data | Write successful |
| | | 7 | DL | Error Code | See Error Messages |
| Factory Default | Send | 4 | DL | no data | Restore Default (active low) for VSH Restore Default (active high) for VSI/VSM, VSL |
| | | | | 5 | DL |
| | 7 | DL | Error Code | See Error Messages | |

5.2.3 Sensor Transition (ST)

| Mode | Sequence | AC | CMD | Data | Description |
|-------|----------|------------|------------------------------------|------------------|--|
| Read | Send | 0 | ST | no data | |
| | Receive | 1 | ST | 0 | Direct Switch VSR, VSL: 1 mbar VSH: 4E-4 mbar VSM: 1E-3 mbar |
| | | | | 1 | Continuous Transition between VSR, VSL: 5 to 15 mbar VSH: 1E-3 to 2E-3 mbar VSM: 1E-3 to 2E-3 mbar (default) |
| | | | | 2 | Continuous Transition between VSH: 2E-3 to 5E-3 mbar |
| | | | | F[float]T[float] | Custom Continuous Transition (F)rom [float] (T)o [float], float [mbar] |
| | | | | D[float] | Custom Direct Switch D[float], float in [mbar] |
| 7 | ST | Error Code | See Error Messages | | |
| Write | Send | 2 | ST | 0 | Direct Switch VSR, VSL: 1 mbar VSH: 4E-4 mbar |

| | | | | | |
|-----------------|---------|---|----|------------------|--|
| | | | | | VSM: 1E-3 mbar |
| | | | | 1 | Continuously Transition between VSR, VSL: 5 to 15 mbar VSH: 1E-3 to 2E-3 mbar VSM: 1E-3 to 2E-3 mbar (default) |
| | | | | 2 | Continuously Transition between VSH: 2E-3 to 5E-3 mbar |
| | | | | F[float]T[float] | Custom Continuous Transition (F)rom [float] (T)o [float], float [mbar] VSR: 1 mbar to 20 mbar VSH: 4E-4 mbar to 1E-2 mbar VSM: 4E-4 to 2E-3 mbar |
| | | | | D[float] | Custom Direct Switch D[float], float in [mbar] VSR: 1 mbar to 20 mbar VSH: 4E-4 mbar to 1E-2 mbar VSM: 4E-4 to 2E-3 mbar |
| | Receive | 3 | ST | no data | Write successful |
| | | 7 | ST | Error Code | See Error Messages |
| Factory Default | Send | 4 | ST | no data | Restore Default |
| | Receive | 5 | ST | no data | Restore Default successful |
| | | 7 | ST | Error Code | See Error Messages |

5.2.4 Cathode Control (CC)

All modifications with Cathode Control are temporary.

| Mode | Sequence | AC | CMD | Data | Description |
|-----------------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | CC | no data | |
| | Receive | 1 | CC | 0 | Cathode is off |
| | | | | 1 | Cathode is on (default) |
| | | 7 | CC | Error Code | See Error Messages |
| Write | Send | 2 | CC | 0 | Cathode off |
| | | | | 1 | Cathode on (default) |
| | Receive | 3 | CC | no data | Write successful |
| | | | | 7 | Error Code |
| Factory Default | Send | 4 | CC | no data | Restore Default |
| | Receive | 5 | CC | no data | Restore Default successful |
| | | 7 | CC | Error Code | See Error Messages |

5.2.5 Cathode Control Mode (CM)

All modifications with Cathode Control Mode are permanent.

| Mode | Sequence | AC | CMD | Data | Description |
|-------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | CM | no data | |
| | Receive | 1 | CM | 0 | User Control (manually) |
| | | | | 1 | Automatic Control (default) |
| | | 7 | CM | Error Code | See Error Messages |
| Write | Send | 2 | CM | 0 | User Control (manually) |
| | | | | 1 | Automatic Control (default) |
| | Receive | 3 | CM | no data | Write successful |

| | | | | | |
|-----------------|---------|---|----|------------|------------------------------------|
| | | 7 | | Error Code | See Error Messages |
| Factory Default | Send | 4 | CM | no data | Restore Default |
| | Receive | 5 | CM | no data | Restore Default successful |
| | | 7 | CM | Error Code | See Error Messages |

5.2.6 Filament Control (FC)

| Mode | Sequence | AC | CMD | Data | Description |
|-----------------|----------|----|------------|------------------------------------|--|
| Read | Send | 0 | FC | no data | |
| | Receive | 1 | FC | 0 | Switch to Fil. 2 if Fil. 1 is defect (default) |
| | | | FC | 1 | Force use Fil. 1 |
| | | | FC | 2 | Force use Fil. 2 |
| | | | FC | 3 | Toggle Filament if pressure > 1 mbar |
| | 7 | FC | Error Code | See Error Messages | |
| Write | Send | 2 | FC | 0 | Switch to Fil. 2 if Fil. 1 is defect (default) |
| | | | FC | 1 | Force use Fil. 1 |
| | | | FC | 2 | Force use Fil. 2 |
| | | | FC | 3 | Toggle Filament if pressure > 1 mbar |
| | Receive | 3 | FC | no data | Write successful |
| | 7 | FC | Error Code | See Error Messages | |
| Factory Default | Send | 4 | FC | no data | Restore Default |
| | Receive | 5 | FC | no data | Restore Default successful |
| | | 7 | FC | Error Code | See Error Messages |

5.2.7 Filament Number (FN)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | FN | no data | |
| | Receive | 1 | FN | 1 or 2 | Return current filament number |
| | | 7 | FN | Error Code | See Error Messages |

5.2.8 Filament Status (FS)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|------------|------------------------------------|----------------------------|
| Read | Send | 0 | FS | no data | |
| | Receive | 1 | FS | 0 | Filament 1 and 2 ok |
| | | | FS | 1 | Filament 1 defective |
| | | | FS | 2 | Filament 2 defective |
| | | | FS | 3 | Filament 1 and 2 defective |
| | 7 | FS | Error Code | See Error Messages | |

5.2.9 Gas Correction Factor 1, 3, 4 (C1, C3, C4)

| Mode | Sequence | AC | CMD | Data | Description |
|-------|----------|----|------------|--------------------|------------------------------------|
| Read | Send | 0 | C1 | no data | |
| | | | C3 | no data | |
| | | | C4 | no data | |
| | Receive | 1 | C1 | float (2 decimals) | Factor for Pirani |
| | | | C3 | float (2 decimals) | Factor for Hot Cathode |
| | | | C4 | float (2 decimals) | Factor for Cold Cathode |
| | | 7 | C1 C3/4 | Error Code | See Error Messages |
| Write | Send | 2 | C1 | float | New factor for Pirani (0.2 to 8.0) |

| | | | | | |
|-----------------|---------|------|------------|------------------------------------|--|
| | | | C3 | float | New factor for Hot Cathode (0.2 to 8.0) |
| | | | C4 | float | New factor for Cold Cathode (0.2 to 8.0) |
| | Receive | 3 | C1 | no data | Write successful |
| | | 7 | C3/4 | Error Code | See Error Messages |
| Factory Default | Send | 4 | C1 | no data | Restore Default Factor for Pirani |
| | | | C3 | no data | Restore Default Factor for Hot Cathode |
| | | | C4 | no data | Restore Default Factor for Cold Cathode |
| | Receive | 5 | C1 | no data | Restore successful |
| 7 | | C3/4 | Error Code | See Error Messages | |

5.2.10 Panel Status (PS)

| Mode | Sequence | AC | CMD | Data | Description |
|-------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | PS | no data | |
| | Receive | 1 | PS | 0 | Panel unlocked |
| | | | | 1 | Panel locked |
| | | 7 | PS | Error Code | See Error Messages |
| Write | Send | 2 | PS | 0 | Unlock Panel |
| | | | | 1 | Lock Panel |
| | Receive | 3 | PS | no data | Write successful |
| | | 7 | PS | Error Code | See Error Messages |

5.2.11 Controller Status (CS)

| Mode | Sequence | AC | CMD | Data | Description |
|-------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | CS | no data | |
| | Receive | 1 | CS | 0 | Controller is off |
| | | | | 1 | Controller is on |
| | | 7 | CS | Error Code | See Error Messages |
| Write | Send | 2 | CS | 0 | Switch Controller off |
| | | | | 1 | Switch Controller on |
| | Receive | 3 | CS | no data | Write successful |
| | | 7 | CS | Error Code | See Error Messages |

5.3 Transmitter Parameter

5.3.1 Type of Device (TD)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|-------------------------------------|
| Read | Send | 0 | TD | no data | |
| | Receive | 1 | TD | string | Identification string of the device |
| | | 7 | TD | Error Code | See Error Messages |

5.3.2 Product Name (PN)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | PN | no data | |
| | Receive | 1 | PN | string | Product Name, e.g. VSP53D |
| | | 7 | PN | Error Code | See Error Messages |

5.3.3 Serial Number Device (SD)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | SD | no data | |
| | Receive | 1 | SD | string | Serial Number of Device |
| | | 7 | SD | Error Code | See Error Messages |

5.3.4 Serial Number Head (SH)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | SH | no data | |
| | Receive | 1 | SH | string | Serial Number of Sensor Head |
| | | 7 | SH | Error Code | See Error Messages |

5.3.5 Baud Rate (BR)

| Mode | Sequence | AC | CMD | Data | Description |
|-------|----------|----|-----|-------------|---|
| Write | Send | 2 | BR | [baud rate] | Use baud rate as data 9600, 14400, 19200, 28800, 38400, 57600, 115200 |
| | | | | Receive | 3 |
| | | 7 | BR | Error Code | See Error Messages |

Note: If no error, the new baud will be activated after the receive sequence.

5.3.6 Response Delay (RD)

| Mode | Sequence | AC | CMD | Data | Description |
|-------|----------|----|-----|------------|--|
| Read | Send | 0 | RD | no data | |
| | Receive | 1 | RD | int | Response delay in μs |
| | | 7 | RD | Error Code | See Error Messages |
| Write | Send | 2 | RD | int | New response delay in μs (Valid values from 1 to 99999 μs) |
| | | | | Receive | 3 |
| | | 7 | RD | Error Code | See Error Messages |

Note: The change of the response delay is always temporarily. After switching the device on/off or sending a Device Restart (DR) command the device will use the default value again.

5.3.7 Version Device (VD)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | VD | no data | |
| | Receive | 1 | VD | string | Version Device |
| | | 7 | VD | Error Code | See Error Messages |

5.3.8 Version Firmware (VF)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | VF | no data | |
| | Receive | 1 | VF | string | Version Firmware |
| | | 7 | VF | Error Code | See Error Messages |

5.3.9 Version Bootloader (VB)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|------------------------------------|
| Read | Send | 0 | VB | no data | |
| | Receive | 1 | VB | string | Version Bootloader |
| | | 7 | VB | Error Code | See Error Messages |

5.3.10 Device Restart (DR)

| Mode | Sequence | AC | CMD | Data | Description |
|-------|----------|----|-----|------------|------------------------------------|
| Write | Send | 2 | DR | no data | |
| | Receive | 3 | DR | no data | |
| | | 7 | DR | Error Code | See Error Messages |

Note: If no error, device will restart after the receive sequence.

5.3.11 Analog Output Characteristic (OC)

| Mode | Sequence | AC | CMD | Data | Description |
|-----------------|----------|----|-----|-------------|------------------------------------|
| Read | Send | 0 | OC | no data | |
| | Receive | 1 | OC | Data String | See Description Data String |
| | | 7 | OC | Error Code | See Error Messages |
| Write | Send | 2 | OC | Data String | See Description Data String |
| | Receive | 3 | OC | no data | Write successful |
| | | 7 | OC | Error Code | See Error Messages |
| Factory Default | Send | 4 | OC | no data | Restore Default |
| | Receive | 5 | OC | no data | Restore Default successful |
| | | 7 | OC | Error Code | See Error Messages |

Description Data String:

The data string for the analog output characteristic has a mutable length and is divided into eight sub data contents. The order of sub data is mandatory.

| Data | Sub Term | Sub Data | Description |
|-------------|----------|----------------------|---|
| DATA | TYPE | Log | Logarithmic Output |
| | | Lin | Linear Output |
| | GAIN | G[float] | Gain shortcut "G" followed by float |
| | OFFSET | O[float] | Offset shortcut "O" followed by voltage float in [V] |
| | LOW. L. | L[float] | Lower Limit shortcut "L" followed by voltage float in [V] |
| | UPP. L. | L[float] | Upper Limit shortcut "L" followed by voltage float in [V] |
| | UNDER. | U[float] | Underrange shortcut "U" followed by voltage float in [V] |
| | OVER. | O[float] | Overrange shortcut "O" followed by voltage float in [V] |
| | FAULT | F[float] | Fault shortcut "F" followed by voltage float in [V] |
| Data Source | D[int] | Optional data source | |

For table function:

| Data | Sub Term | Sub Data | Description |
|------|----------|----------|--|
| DATA | Type | Tab | Logarithmic Output |
| | Size | S[int] | Table size count, maximum is 64 |
| | UNDER. | U[float] | Underrange shortcut "U" followed by voltage float in [V] |

| | | | |
|--|-------------|----------|---|
| | OVER. | O[float] | Overrange shortcut "O" followed by voltage float in [V] |
| | FAULT | F[float] | Fault shortcut "F" followed by voltage float in [V] |
| | Data Source | D[int] | Optional data source |

| Data | Sub Term | Sub Data | Description |
|------|----------|----------|--|
| DATA | Type | Tab | Logarithmic Output |
| | Entry | E[int] | Entry index |
| | Pressure | P[float] | Pressure shortcut "P" followed by voltage float in [V] |
| | Voltage | U[float] | Voltage shortcut "U" followed by voltage float in [V] |

Data Package Syntax for Analog Output Characteristic:

| DATA | | | | | | | | | | | | | | | | |
|------|---|---|------|-------|--------|-------|---------|-------|---------|-------|--------|-------|-------|-------|-------|-------|
| TYPE | | | GAIN | | OFFSET | | LOW. L. | | UPP. L. | | UNDER. | | OVER. | | FAULT | |
| L | o | g | G | float | O | float | L | float | L | float | U | float | O | float | F | float |
| L | i | n | G | float | O | float | L | float | L | float | U | float | O | float | F | float |

Example: Read Analog Output Characteristic

Sequence Send:

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|-----|---|---|----|-----|---|-----|---|----|----|
| ADR | | | AC | CMD | | LEN | | CS | CR |
| 0 | 0 | 1 | 0 | O | C | 0 | 0 | s | CR |

For a table entry:

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 |
|-----|---|---|----|-----|---|-----|---|------|-------|----|----|
| ADR | | | AC | CMD | | LEN | | Type | Index | CS | CR |
| 0 | 0 | 1 | 0 | O | C | 0 | 2 | E | 1 | k | CR |

Sequence Receive:

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | ... | n | n+1 | n+2 |
|-----|---|---|----|-----|---|-----|---|---------|-----|---|-----|-----|
| ADR | | | AC | CMD | | LEN | | DATA | | | CS | CR |
| 0 | 0 | 1 | 1 | O | C | 3 | 7 | 37 Byte | | | I | CR |

The content of DATA will be:

| DATA | | | | | | | | | | | | | | | | |
|------|---|---|------|-----|--------|-----|---------|-----|---------|------|--------|-----|-------|-----|-------|-----|
| TYPE | | | GAIN | | OFFSET | | LOW. L. | | UPP. L. | | UNDER. | | OVER. | | FAULT | |
| L | o | g | G | 1.0 | O | 5.5 | L | 0.0 | L | 10.5 | U | 0.9 | O | 9.2 | F | 0.4 |

5.3.12 Operating Hours (OH)

| Mode | Sequence | AC | CMD | Data | Description |
|------|----------|----|-----|------------|---|
| Read | Send | 0 | OH | 0 | Operating hours (VSR, VSL, VSP, VCP) |
| | | | | 1 | Operating hours (VSH, VSM/VSI) |
| | Receive | 1 | OH | int | Operating hours in 15 minutes interval (VSR, VSL, VSP, VCP) |
| | | | | string | Operating hours of device and cathode, each in 15 minutes interval (VSH, VSM/VSI) |
| | | 7 | OH | Error Code | See Error Messages |

Example: Operating hours for VSR53D, Address 1

Sequence Receive:

| | | | | | | | | | | | |
|-----|---|---|----|-----|---|-----|---|------|---|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 |
| ADR | | | AC | CMD | | LEN | | DATA | | CS | CR |
| 0 | 0 | 1 | 1 | O | H | 0 | 2 | 8 | 5 | h | CR |

Operating hours device: $85/4 = 21.25$

Example: Operating Hours for VSM77D, Address 1

Sequence Receive:

| | | | | | | | | | | | | | | |
|-----|---|---|----|-----|---|-----|---|------|---|----|----|----|----|----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 |
| ADR | | | AC | CMD | | LEN | | DATA | | | | CS | CR | |
| 0 | 0 | 1 | 1 | O | H | 0 | 5 | 4 | 2 | C | 3 | 6 | P | CR |

Operating hours device: $42/4 = 10.5$

Operating hours cold cathode: $36/4 = 9$

6 Warnings and Error Messages

If any error occurs, you will receive a feedback from the device with access code 7 and a short message in DATA to explain what kind of error happened.

| DATA | Description |
|--------|---|
| NO_DEF | Command is not valid (not defined) for the device, e.g. Degas (DG) for VSR |
| _LOGIC | Access Code is not valid or execution of command is not logical |
| _RANGE | Error if any data value in send sequence is out of range, e.g. value too high for a gas correction factor |
| ERROR1 | Sensor is defect or stacked out |
| SYNTAX | Command is valid, but the syntax in data is wrong or the selected mode in data is not valid for your device |
| LENGTH | Command is valid, but the length of data is out of expected range |
| _CD_RE | Calibration Data Read Error |
| _EP_RE | EEPROM Read Error |
| _UNSUP | Unsupported Data, e.g. no valid value for baud rate |
| _SEDIS | Sensor element disabled, e.g. read measurement of cathode if cathode is disabled |

7 ASCII Table

| Dec | Hex | ASC |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| 0 | 00 | NUL | 22 | 16 | SYN | 44 | 2C | , | 66 | 42 | B | 88 | 58 | X | 110 | 6E | n |
| 1 | 01 | SOH | 23 | 17 | ETB | 45 | 2D | - | 67 | 43 | C | 89 | 59 | Y | 111 | 6F | o |
| 2 | 02 | STX | 24 | 18 | CAN | 46 | 2E | . | 68 | 44 | D | 90 | 5A | Z | 112 | 70 | p |
| 3 | 03 | ETX | 25 | 19 | EM | 47 | 2F | / | 69 | 45 | E | 91 | 5B | [| 113 | 71 | q |
| 4 | 04 | BOT | 26 | 1A | SUB | 48 | 30 | 0 | 70 | 46 | F | 92 | 5C | \ | 114 | 72 | r |
| 5 | 05 | ENQ | 27 | 1B | ESC | 49 | 31 | 1 | 71 | 47 | G | 93 | 5D |] | 115 | 73 | s |
| 6 | 06 | ACK | 28 | 1C | FS | 50 | 32 | 2 | 72 | 48 | H | 94 | 5E | ^ | 116 | 74 | t |
| 7 | 07 | BEL | 29 | 1D | GS | 51 | 33 | 3 | 73 | 49 | I | 95 | 5F | _ | 117 | 75 | u |
| 8 | 08 | BS | 30 | 1E | RS | 52 | 34 | 4 | 74 | 4A | J | 96 | 60 | ` | 118 | 76 | v |
| 9 | 09 | TAB | 31 | 1F | US | 53 | 35 | 5 | 75 | 4B | K | 97 | 61 | a | 119 | 77 | w |
| 10 | 0A | LF | 32 | 20 | SP | 54 | 36 | 6 | 76 | 4C | L | 98 | 62 | b | 120 | 78 | x |
| 11 | 0B | VT | 33 | 21 | ! | 55 | 37 | 7 | 77 | 4D | M | 99 | 63 | c | 121 | 79 | y |
| 12 | 0C | FF | 34 | 22 | „ | 56 | 38 | 8 | 78 | 4E | N | 100 | 64 | d | 122 | 7A | z |
| 13 | 0D | CR | 35 | 23 | # | 57 | 39 | 9 | 79 | 4F | O | 101 | 65 | e | 123 | 7B | { |
| 14 | 0E | SOH | 36 | 24 | \$ | 58 | 3A | : | 80 | 50 | P | 102 | 66 | f | 124 | 7C | |
| 15 | 0F | SI | 37 | 25 | % | 59 | 3B | ; | 81 | 51 | Q | 103 | 67 | g | 125 | 7D | } |
| 16 | 10 | DLE | 38 | 26 | & | 60 | 3C | < | 82 | 52 | R | 104 | 68 | h | 126 | 7E | ~ |
| 17 | 11 | DC1 | 39 | 27 | , | 61 | 3D | = | 83 | 53 | S | 105 | 69 | i | 127 | 7F | DEL |
| 18 | 12 | DC2 | 40 | 28 | (| 62 | 3E | > | 84 | 54 | T | 106 | 6A | j | | | |
| 19 | 13 | DC3 | 41 | 29 |) | 63 | 3F | ? | 85 | 55 | U | 107 | 6B | k | | | |
| 20 | 14 | DC4 | 42 | 2A | * | 64 | 40 | @ | 86 | 56 | V | 108 | 6C | l | | | |
| 21 | 15 | NAK | 43 | 2B | + | 65 | 41 | A | 87 | 57 | W | 109 | 6D | m | | | |

8 Command comparison between old and new protocol

| Old Protocol | New Protocol | Compatibility of Data | Description |
|------------------------------------|---|-----------------------|---|
| Type (T) | Type of Device (TD) | Yes | |
| Measurement (M) | Measurement Value (MV) | No | old: 6 Byte fixed, coded new: float value |
| Setpoint (S,s) Hysteresis (H,h) | Relay 1,2,3,4 (R1,R2,R3,R4) | No | Complete overhaul, see command description |
| Parameter Set (P,p) | | | not supported anymore |
| Correction Factor (C,c) | Gas Correction Factor 1,3,4 (C1, C3, C4) | No | old: integer multiplied by 100 new: float value and distinction between hot and cold cathode possible |
| Adjustment (j) | Adjust High (AH) Adjust Low (AL) | No | Complete overhaul, see command description |
| Start/Stop Control (A,a) | Controller Status (CS) | Yes | |
| Lock Keyboard (K,k) | Panel Status (PS) | Yes | |
| Degas (D,d) | Degas (DG) | Yes | |
| Filament Number (F) | Filament Number (FN) | No | old: 0=Fil. 1, 1=Fil. 2 new: 1=Fil. 1, 2=Fil. 2 |
| Sensor Transition (W,w) | Sensor Transition (ST) | partly | Complete overhaul, see command description |
| Cold Cathode (I,i) | Cathode Control (CC) | Yes | |
| Display Unit (U,u) | Display Unit (DU) | No | Complete overhaul, see command description |

9 Document History

| Date | Version | Author | Changes |
|------------|---------|--------|---|
| 12.04.2016 | 2.0.0 | SJ | first public release |
| 18.04.2016 | 2.0.1 | SJ | Update Sensor Transition (ST) Custom Continuous Transition and Custom Direct Switch Added: Valid Pressure Ranges for VSR, VSH and VSM |
| | | | Update Gas Correction Factor 1, 3, 4 (C1, C3, C4) Fixed: Write Command, wrong sensor principle for C3 and C4 Added: Valid Factor Ranges for C1, C3 and C4 |
| 26.04.2016 | 2.0.2 | SJ | Update Response Delay (RS) Added: Valid Value Range for RS |
| 28.06.2016 | 2.0.3 | SJ | Added: Degas Logic (DL) |
| | | | Fixed some typing errors in these commands: Adjust Low (AL) Device Restart (DR) Analog Output Characteristic (OC) |
| | | | Added: Adjust Low (AJ), Write with float as data to adjust low to a specific pressure |
| 16.09.2016 | 2.0.4 | SJ | Changed parameter descriptions with [hPa] to [mbar]. However, the value itself will not change, but mbar is the default unit: Changes done in: Measurement Range (MR) Measurement Value (MV) Measurement Value 1, 2, 3, 4 (M1, M2, M3, M4) Adjust High (AH) Adjust Low (AL) Relay 1, 2, 3, 4 (R1, R2, R3, R4) Sensor Transition (ST) Filament Control (FC) |
| | | | Update Response Delay (RD) Fixed typing error, changed "99999 μ " to "99999 μ s" |
| 12.10.2016 | 2.0.5 | SJ | Update Display Unit (DU) Existing Access Code "Factory Default" wasn't documented |
| 17.10.2016 | 2.0.6 | SJ | Update Degas (DG) and DeGas Logic (DL) Added some information to both commands. |
| | | | Removed Version Head (VH) from valid command list for Smartline Transmitter |
| 03.04.2017 | 2.0.7 | SJ | Added: Cathode Control Mode (CM) Read, Write and Factory Default |
| | | | Added: Display Orientation (DO) Read, Write and Factory Default |
| | | | Added Overrange and Underrange Message to Command Measurement Value (MV) and Measurement Value 1,2,3,4 (M1/4) |
| | | | Reorganization of Command Overview section into Main Commands, Sensor Parameter and Device Information |
| 25.07.2017 | 2.0.8 | MN | Added: VD14 |
| 04.08.2017 | 2.0.9 | MN | Added: VSM Digital Logic "DL" |
| 16.10.2017 | 2.1.0 | MN | Added: valid display units |
| 13.11.2017 | 2.1.1 | MN | Added: Analog Output Characteristic Table Function |
| 21.12.2018 | 2.1.2 | MN | Added: Measurement Value M6, M7 |
| | | | Added: Display Data Source |

| | | | |
|------------|-------|----|---|
| | | | Added: Data Source Parameter for R1, R2, OC |
| 19.12.2019 | 2.1.3 | WS | Fixed: Typos Update: Adjust functions, parameter DL Added: Operating Hours (OH) |